

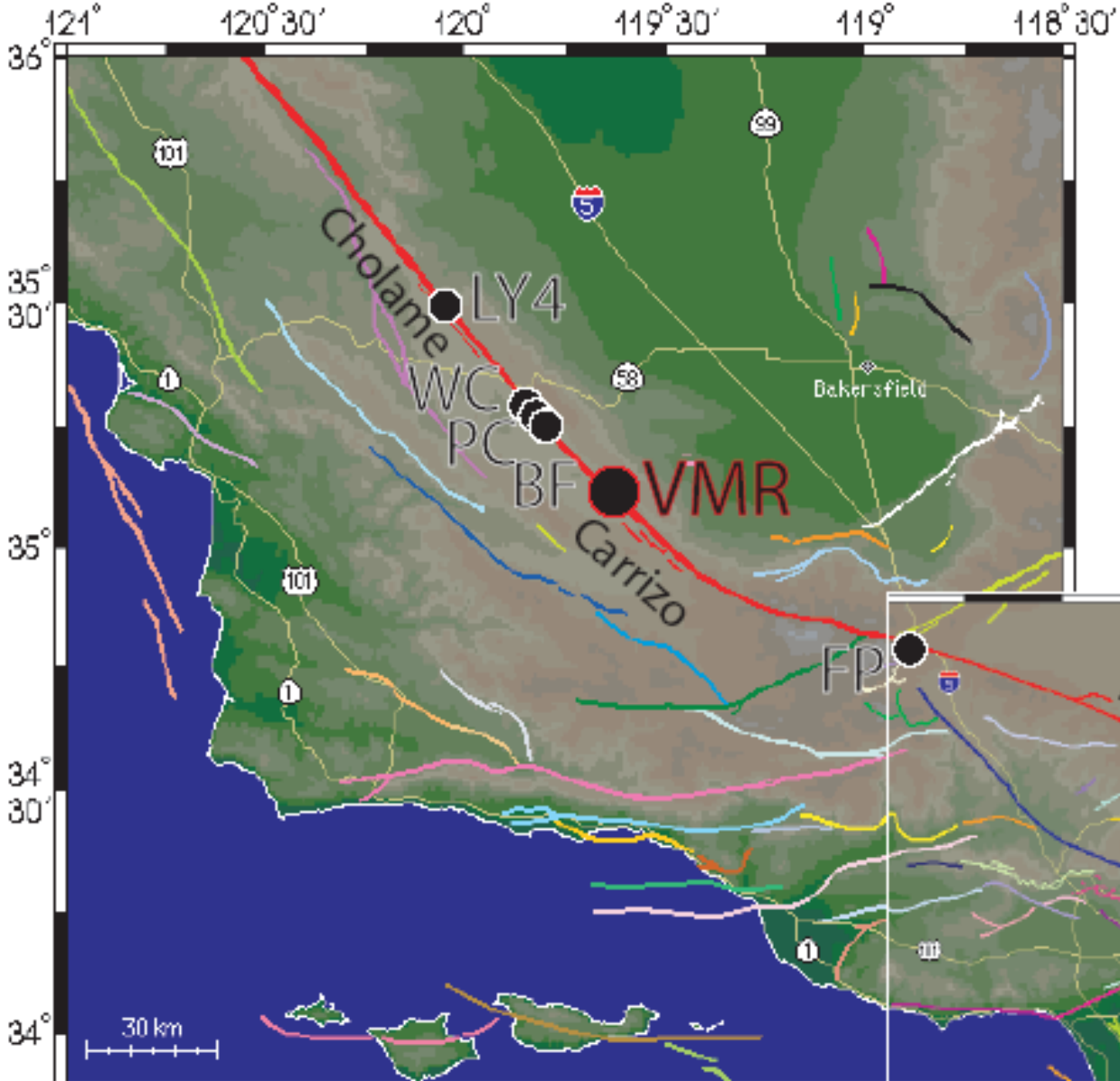
Simple rotations

Ramón Arrowsmith

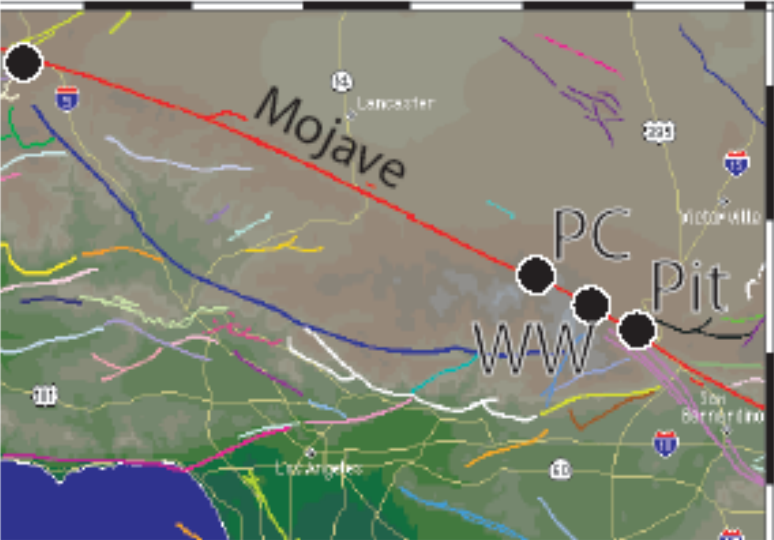
ramon.arrowsmith@asu.edu

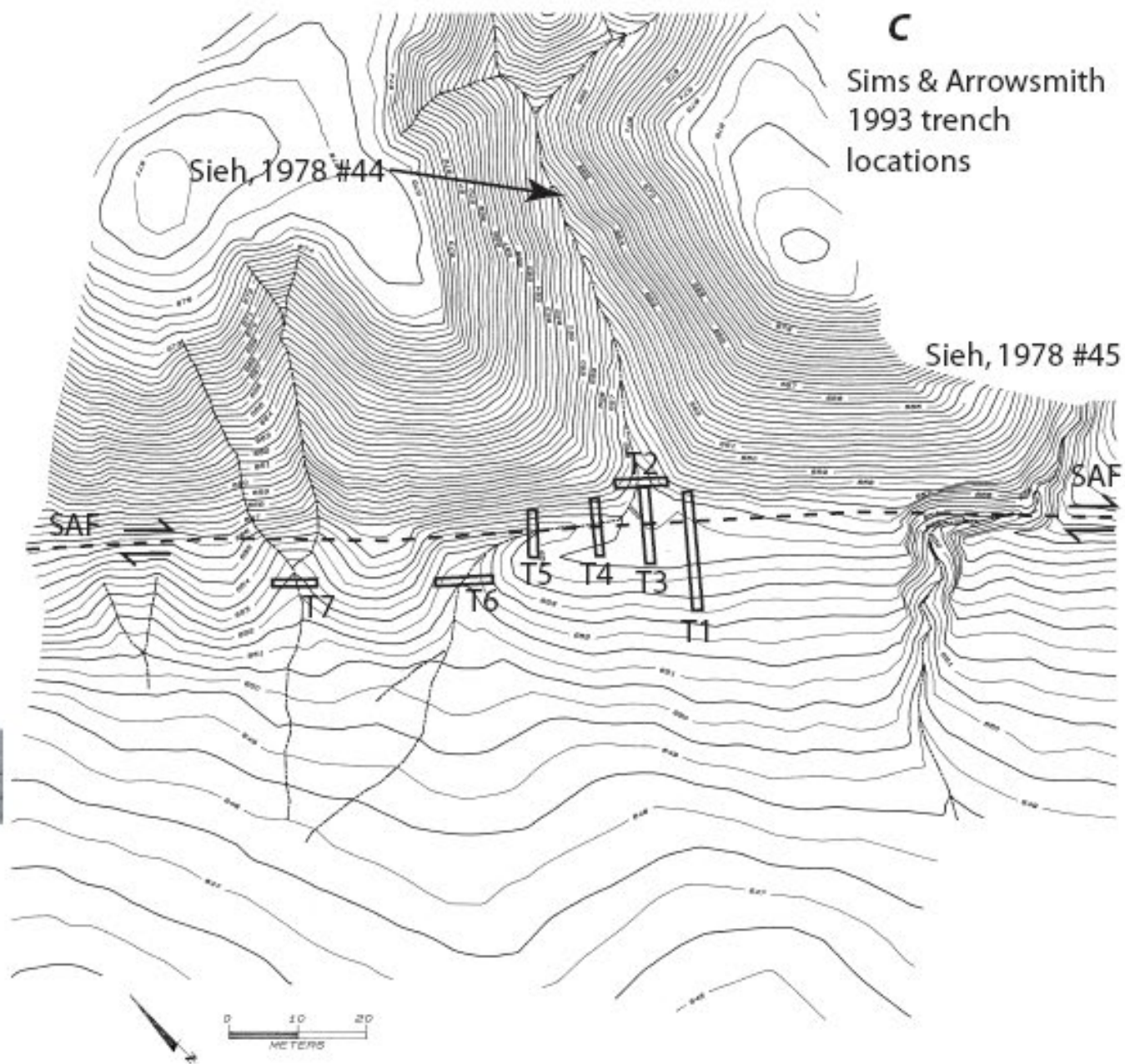
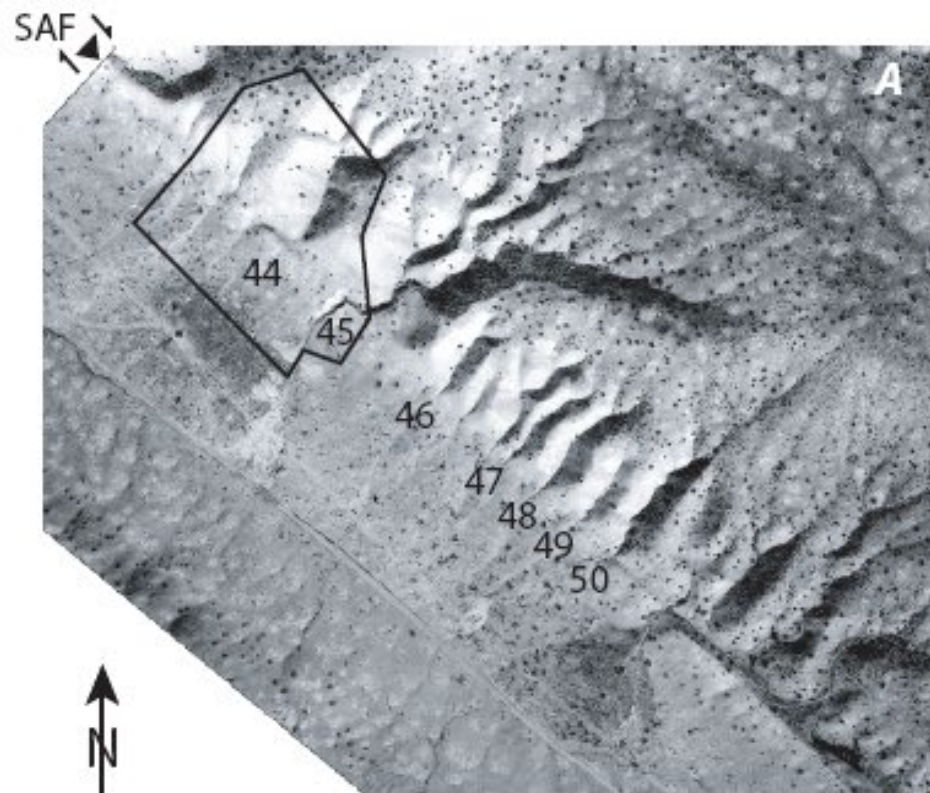
Example: Van Matre Ranch paleoseismic Site

Bulletin of the Seismological Society of America, Vol. 96, No. 1, pp. 33-47, February 2006, doi: 10.1785/0120050094



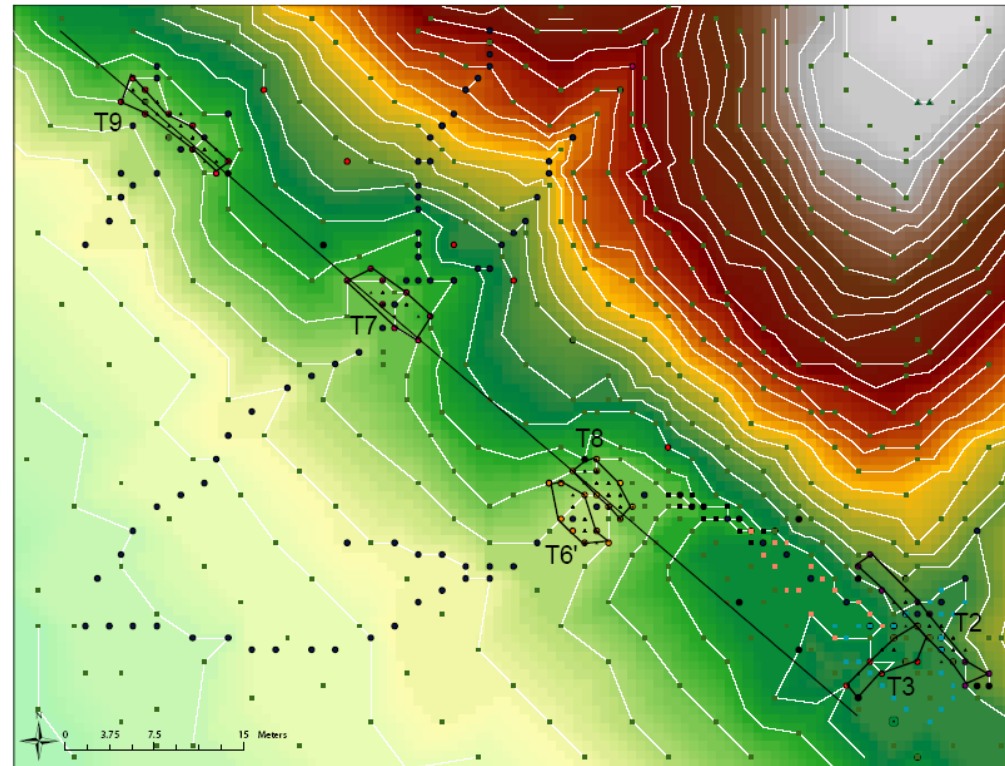
Stream Channel Offset and Late Holocene Slip Rate of the San Andreas Fault at the Van Matre Ranch Site, Carrizo Plain, California
by Gabriela R. Noriega, J Ramón Arrowsmith, Lisa B. Grant, and Jeri J. Young





2004 Measurements					UTM/GPS		
	E	N	H		E	N	H
0	1000	1000	100	Base (1993 point 2)	254069	3893433	645
3	1097.861	1001.704	128.1	shot to station 3	254139	3893503	667
70	1051.88	1038.702	105.6	T9_control	254080	3893496	640
71	1053.164	1028.231	106.5	T7_control	254088	3893491	650
72	1053.449	1000.974	105.1	T6_prime_control	254108	3893472	652
73	1056.372	1000.414	105.3	T8_control	254109	3893473	651
74	1067.253	963.185	108.3	T2_control	254143	3893455	653
75	1058.533	969.826	107.3	T3_control	254133	3893453	652

How do we get the local coords into the global one?
 And how to project to the fault parallel





B



SAF





16 September 2022

GLG510 Advanced Structural Geology

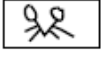


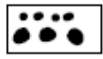
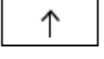
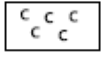
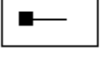
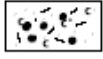
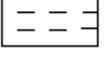

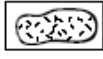


Explanation

Logging symbols

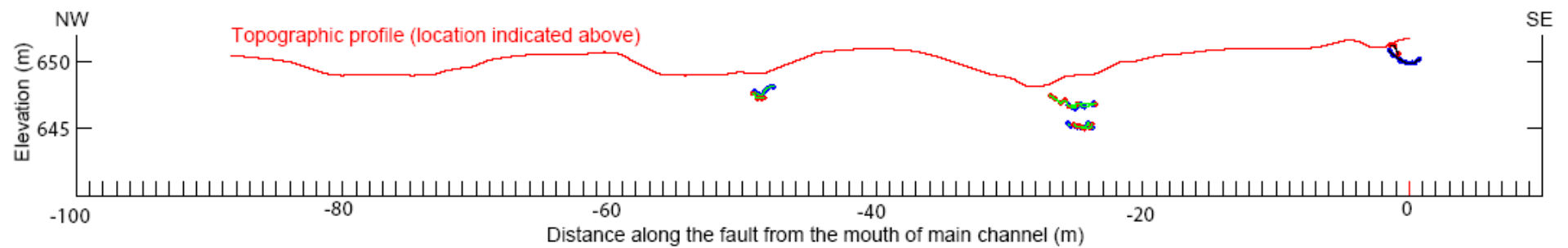
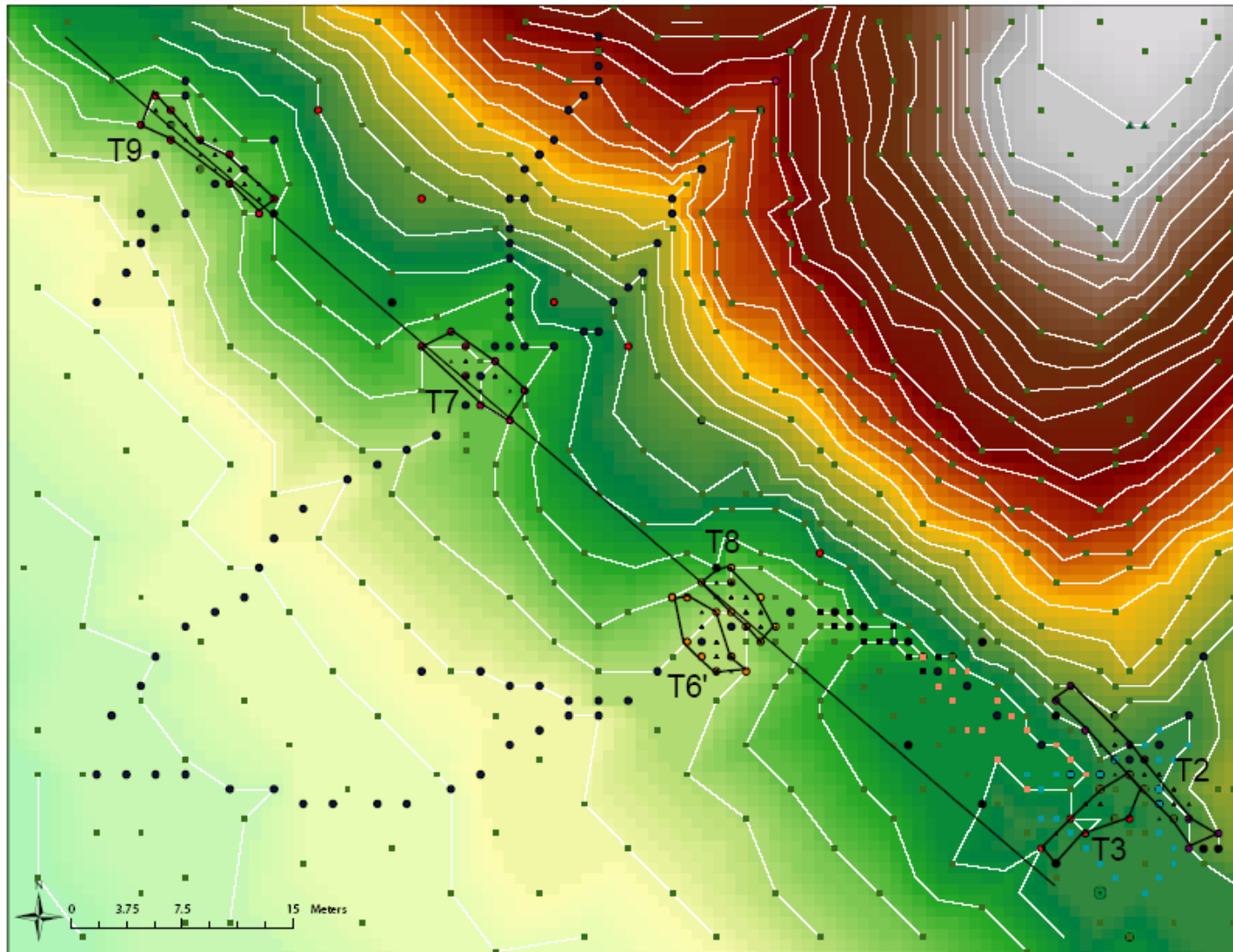
- sharp contact
- - - - approximately located contact
- 8 — gradational contact in cm
- ? — ? — location of contact is questionable
- T2_1 ¹⁴C sample location
- 210 Unit label

Lithologic Symbols

- | | | | |
|---|----------------|---|----------------------------|
|  | burrows |  | fine-medium sand |
| k | carbonate |  | coarse sand |
| gyp | gypsum |  | cobbles and pebbles |
|  | fining upward |  | clay |
|  | carbon sample |  | colluvium |
|  | laminated silt |  | cobble or boulder to scale |
| | |  | granitic boulder to scale |

“Projection”

Rotate coordinates to Parallel and perpendicular to the fault trace



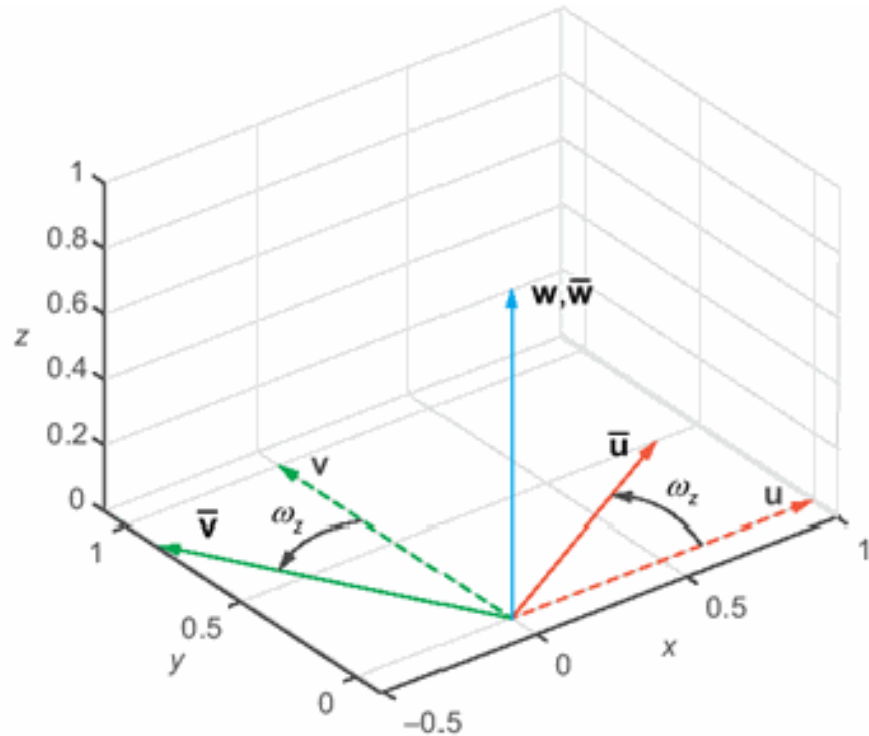


Figure 2.42 Pure rotation of material lines about the z-axis through angle ω_z as tracked by vectors \mathbf{u} , \mathbf{v} , and \mathbf{w} , originally coincident with the coordinate axes. After rotation the new vectors are $\bar{\mathbf{u}}$, $\bar{\mathbf{v}}$, and $\bar{\mathbf{w}}$. The sense of rotation follows a right-hand rule: it is in the direction of the fingers of your right hand with your thumb pointing in the direction of the positive z-axis.

Row times column multiplication

example, the following matrix provides a pure rotation about the z-axis through an angle ω_z for material lines lying in the (x, y)-plane:

$$[\mathbf{R}] = \begin{bmatrix} \cos \omega_z & -\sin \omega_z & 0 \\ \sin \omega_z & \cos \omega_z & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad (2.63)$$

To visualize this rotation consider three unit vectors that overlie material lines extending from the origin along the coordinate axes before rotation (**Figure 2.42**):

$$[\mathbf{u}] = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \quad [\mathbf{v}] = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \quad [\mathbf{w}] = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

These are unit vectors and they are orthogonal. Using $[\mathbf{R}]$ from (2.63) as the pre-multiplier for each vector, we find the rotated vectors:

$$[\bar{\mathbf{u}}] = \begin{bmatrix} \cos \omega_z \\ \sin \omega_z \\ 0 \end{bmatrix}, \quad [\bar{\mathbf{v}}] = \begin{bmatrix} -\sin \omega_z \\ \cos \omega_z \\ 0 \end{bmatrix}, \quad [\bar{\mathbf{w}}] = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad (2.64)$$

```

%rotation demonstration
%VMR example

%data:E N H
coords=[
254069 3893433 645
254139 3893503 667
254080 3893496 640
254088 3893491 650
254108 3893472 652
254109 3893473 651
254143 3893455 653
254133 3893453 652
254065 3893509 999
254134 3893450 999];%last two are the SAF trace

```

```

x=coords(:,1);
y=coords(:,2);

x_mean=mean(x);
y_mean=mean(y);

```

```

figure(1)
clf
plot(x_mean,y_mean,'bo')
hold on
plot(x,y,'k.', 'MarkerSize',15)
plot([x(9) x(10)],[y(9) y(10)],'k-', 'MarkerSize',15)
xlabel('Easting (m)')
ylabel('Northing (m)')
axis equal

```

```

coords(:,1)=coords(:,1)-x_mean;
coords(:,2)=coords(:,2)-y_mean;

```

```

omegaz = 50; %rotation angle in degrees

```

```

R = [cosd(omegaz) -sind(omegaz) 0;
     sind(omegaz) cosd(omegaz) 0;
     0 0 1];

```

```

coords_prime = coords*R;
x_prime=coords_prime(:,1)+x_mean;
y_prime=coords_prime(:,2)+y_mean;

```

```

plot(x_prime,y_prime,'r.', 'MarkerSize',15)
plot([x_prime(9) x_prime(10)],[y_prime(9) y_prime(10)],'r-')

```

